

MULTIAGENT SYSTEM MODELING IN LOGISTICS TASKS FOR EMERGENCY SITUATIONS

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INTRODUCTION

As an emergency situation we can take the situation which was not planned or expected from the schedule or route and which demonstrates replacing problems. The problems could occur in the following situations: closed street, closed bridge, absence of electricity, faults with traffic lights, obstacles on the road etc.

For the solution of these problems Transport Management system is to be developed (TMS).

The mathematic model is a graph where the curves are streets and peaks are crossings of the roads. For replanning the schedule Deijkstra algorithm is used for the shortest way searching from a particular point till the point of destination.

Monte-Carlo method is applied for the for modeling the system of environment development.

For the assessment of model's correspondence to the real situation Flash tool is applied.

TRANSPORT MANAGEMENT SYSTEM

Transport Management system is demonstrated in Fig.1. TMS shows the situation on the roads, taking facts and information, which comes from different sources and notifies on unexpected events on the road.

If this information is obtained TMS proves it, defines the environment situation ,

Sensors are installed at the problematic places of the streets. As the sensors laser

its development automatically asks for additional information, defines the importance of the situation. If the condition is important it automatically switches to the Crisis Management system (CMS). It uses the information, applies the decision making system (DMS), which works with the prognosing of the development course and/or duration and makes a decision on replanning of schedule and/or defining additional transport and/or safety brigadge call. Information System (IS) contains actual IS and Geographic IS (GIS). It consists of all types of information and objects, all transport schedules and routes as well as information of safety service and other. On the basis of the knowledge the information is processed from different sources for the clear and comprehensively idea of the present situation.

TMS obtains data using agents. Co-operation with other agents goes through interface agents.

Information and Communication System (ICS) agents operate with information collection from sensors and other systems, information storage, knowledge reflection, which allows to the systems analyse the knowledge and data transporting through the communication structure.

Subject agents have enough knowledge in the special area for example weather.

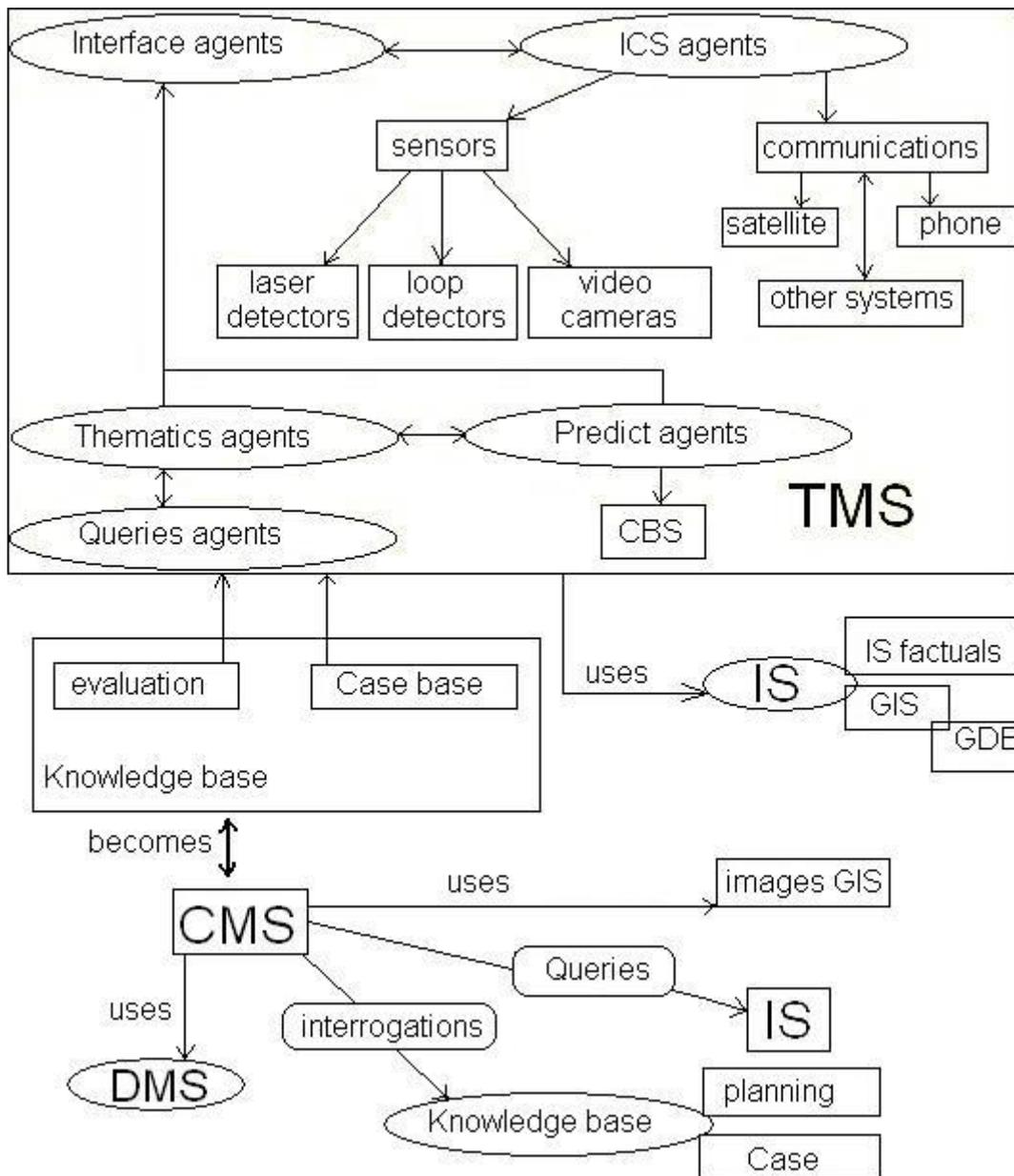
For obtaining data from IS question agents are applied.

Prognosing agents forecast the following situations using information from subject agents, IS and Case based systems (CBS).

detectors are used , which are appllied with ICS agent processing at the real time data,

identify transport, size and speed, define unexpected cases, time and transport density and send the information to TMS, videocameras, with which ICS agents

distinguish unexpected cases and send visual information, loop detectors with the help of which admission time is calculated.



1. figure. Transport Management System

MATHEMATIC MODEL

Mathematic model is developed for Riga region which contains buses, trolleybuses and trams.

This Riga region is shown in Fig.2. With the help of this map A correspondent graph was developed where the streets are curves and peaks are crossings of the roads. The graph is in Fig.3.

The peaks are marked with letters A* for the streets which correspond to some routes

and letter B* for the streets, which could be used for the additional routes. In the graph with oriented pointer only those roads are shown which are one-way streets, the others can be both-directions.

If at any cross (peak) an emergency situation is developed, then this peak is not appropriate and the curves (streets) which go to this peak are not applied.

At the crossroads sensors are installed. Laser detectors are installed at all the peaks of the graph A*, additional road (loop)

detectors are installed also B^* , but videocameras are at all the important crosses on the basic roads – they are the graph peaks: AG, AH, AI, AJ, AK and AL.

The goal is during minimum time through the crossroad where an emergency situation is defined. Goal function:

$$M = \min [t_{Ai}, t_{An}],$$

where M – route,
 t – time,
 A_i – starting peak,
 A_n – final peak.

Sensors of additional roads measure the speed of the transport and with the using of ICS calculate admission time :

$$T = S / V,$$

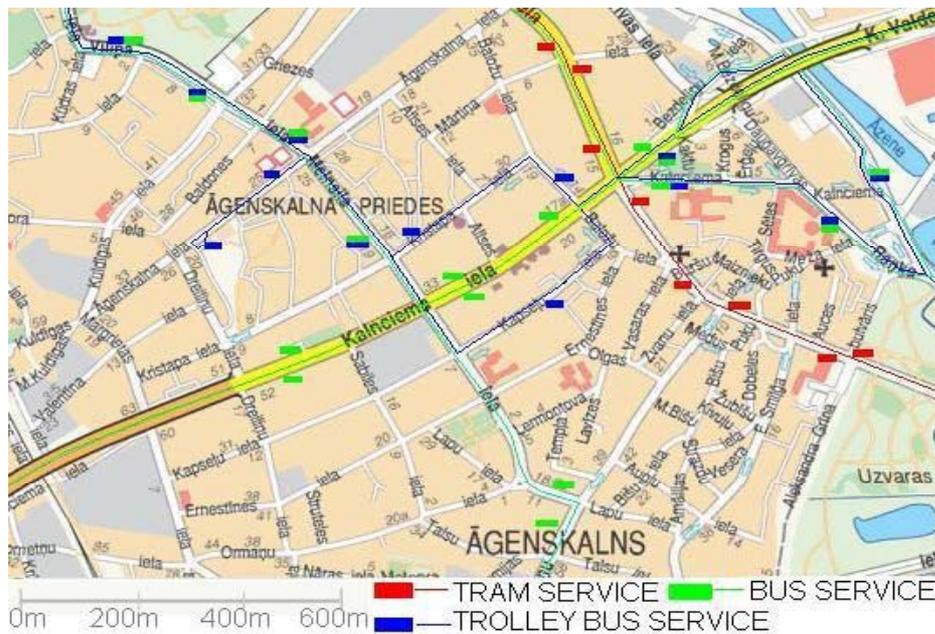
where T – admission time,
 S – length of the curve,
 V – speed of the vehicle.

The obtained T are used as variable of Deiktra algorithm. With this algorithm the shortest way is calculated:

$$T(A_j) = \min [T(A_j), T(p) + w(p, T(A_j))],$$

where $T(A_j)$ – variable for the considered peak,
 p – variable peak which can be considered or not considered at the shortest way.

w – weight between the peaks.
 if $T(p) + w(p, A_j) < T(A_j)$
 then $T(A_j) := T(p) + w(p, A_j)$



2. fig. Riga map

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AUTHOR BIBLIOGRAPHIES

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